

Functional Data Analysis

Lecture – 8

Functional Linear Regression

May 21, 2018

Outline

- 1 Functional Linear Regression With Scalar Response
- 2 Functional Linear Regression With Functional Response

Recall

- The meaning/interpretation of functional data;
- How the real data, which is indeed discrete and finite dimensional, can be put through some analysis involving *smoothing* and *fitting on basis*.
- Established the necessary mathematical language to perform the analysis of such data.
- **Next step:** predicting scalar response on a basis of functional covariates

The functional linear model

- A typical linear regression model is stated as:

$$y_i = \sum_{j=0}^p x_{ij} \beta_j + \epsilon_i, \quad \text{for } i = 1, \dots, N,$$

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- In case the collection $\{t_j\}$ becomes very dense, we could interpret the above as

$$y_i = \int x_i(t) \beta(t) dt + \epsilon_i, \quad \text{for } i = 1, \dots, N.$$

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- **Goal:** To estimate the function $\beta(t)$ using the finite number of observations $\{y_i : i = 1, \dots, N\}$.
- Clearly this is an *ill-posed*, or an *underdetermined* problem (compare the issue with finite dimensional case when $p > N$).
- **Notice:** It is *possible* to solve for β (non-unique) with $\epsilon_i = 0$. In fact, there will be infinitely many solutions (mostly).

Ways to fix the issue of non-uniqueness:

- Use a basis expansion of β :

$$\beta(t) = \sum_{k=1}^K c_k \phi_k(t),$$

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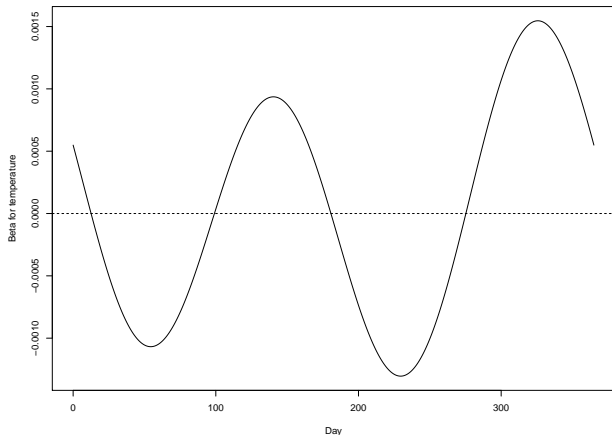
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- Use a principal component analysis to reduce the dimensionality of covariates. This also reduces the problem to a finite dimensional regression problem.

Canadian Weather Data

When regressing log-precipitation on the complete temperature profile, and use Fourier basis with five components, we get the following estimate for $\beta(t)$



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Minimize

$$\begin{aligned} & PENSSE_{\lambda}(\alpha_0, \beta) \\ &= \sum_{i=1}^N \left(y_i - \alpha_0 - \int x_i(t) \beta(t) dt \right)^2 + \lambda \int [L\beta(t)]^2 dt \end{aligned}$$

where L is a differential operator (controlled by the user).

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Note: Choice of smoothing parameter λ is very crucial

Using fPCA for linear regression

Using fPCA, we obtain

$$x_i(t) = \bar{x}(t) + \sum_{j \geq 0} c_{ij} \xi_j(t),$$

where ξ_j are the eigen functions of the sample covariance operator, and $c_{ij} = \int \xi_j(t) (x_i(t) - \bar{x}(t)) dt$.

Then, regression on the principal component scores takes the following form:

$$y_i = \beta_0 + \sum_{j \geq 0} c_{ij} \beta_j + \epsilon_i$$

and to reconcile this with our proposed functional linear regression model, we could interpret

$$\beta(t) = \sum_{j \geq 0} \beta_j \xi_j(t)$$

Statistical Testing

Since in each scenario, the problem reduces to an appropriate finite dimensional problem, we can look back at the usual finite dimensional analysis and use the same analysis.

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Proposed model:

The most generalised version of functional response model takes the following form:

$$y_i(t) = \beta_0(t) + \sum_{j=1}^Q x_{ij}(t) \beta_j(t) + \epsilon(t)$$

which can be rewritten as:

$$\mathbf{y}(t) = \mathbf{Z}(t) \beta(t) + \epsilon(t) \quad \dots [M]$$

where $\mathbf{y}(t)$ is the vector of functions $\{y_i(t)\}$; $\mathbf{Z}(t)$ is the functional design matrix; $\beta(t)$ is the vector of coefficient functions, and $\epsilon(t)$ is the vector of functional noise.

Define:

$$\mathbf{r}(t) = \mathbf{y}(t) - \mathbf{Z}(t) \beta(t) \quad \dots [R]$$

The, $\beta(t)$ is estimated by way of the following constrained minimisation problem:

Minimise

$$LMSSE(\beta) = \int [\mathbf{r}(t)]' \mathbf{r}(t) dt + \sum_{j=1}^Q \lambda_j \int [L_j \beta_j(t)]^2 dt$$

where L_j are appropriate operations (differentiation) to impose smoothness criteria.

Key: Again use basis expansion of $\beta_j(t)$ in terms of $\{\theta_{kj}(t)\}$ as follows:

$$\beta_j(t) = \sum_{k=1}^{K_j} b_{kj} \theta_{kj}(t) = [\theta_j(t)]' \mathbf{b}_j \quad (\text{in matrix notation})$$

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We could rewrite the residual $[R]$ as

$$\mathbf{r}(t) = \mathbf{y}(t) - \mathbf{Z}(t) \Theta(t) \mathbf{b}$$

where $\mathbf{b} = (\mathbf{b}'_1, \dots, \mathbf{b}'_Q)'$ is the column vector of size $K = K_1 + \dots + K_Q$, and

$$\Theta(t) = \begin{bmatrix} \theta'_1 & 0 & \cdots & 0 \\ 0 & \theta'_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \theta'_Q \end{bmatrix}$$

Estimating and testing \mathbf{b}

- After the simplification by invoking the basis assumption the the fitting criterion of minimising $LMSSE(\beta)$ reduces to minimising $LMSSE(\beta)$ with few unknown \mathbf{b} , which is achieved by using simple calculus.

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- However, since all the expressions in $LMSSE$ involve integrals over some parameter space, the practical implementation of estimating \mathbf{b} is achieved by **numerical methods**, and is implemented in the `flda` package.
- Since the estimation has reduced to a finite dimensional computation, the corresponding testing procedure thus remains largely the same as finite dimensional, except that the computations now involve various integrals, which again are incorporated in the `flda` package.